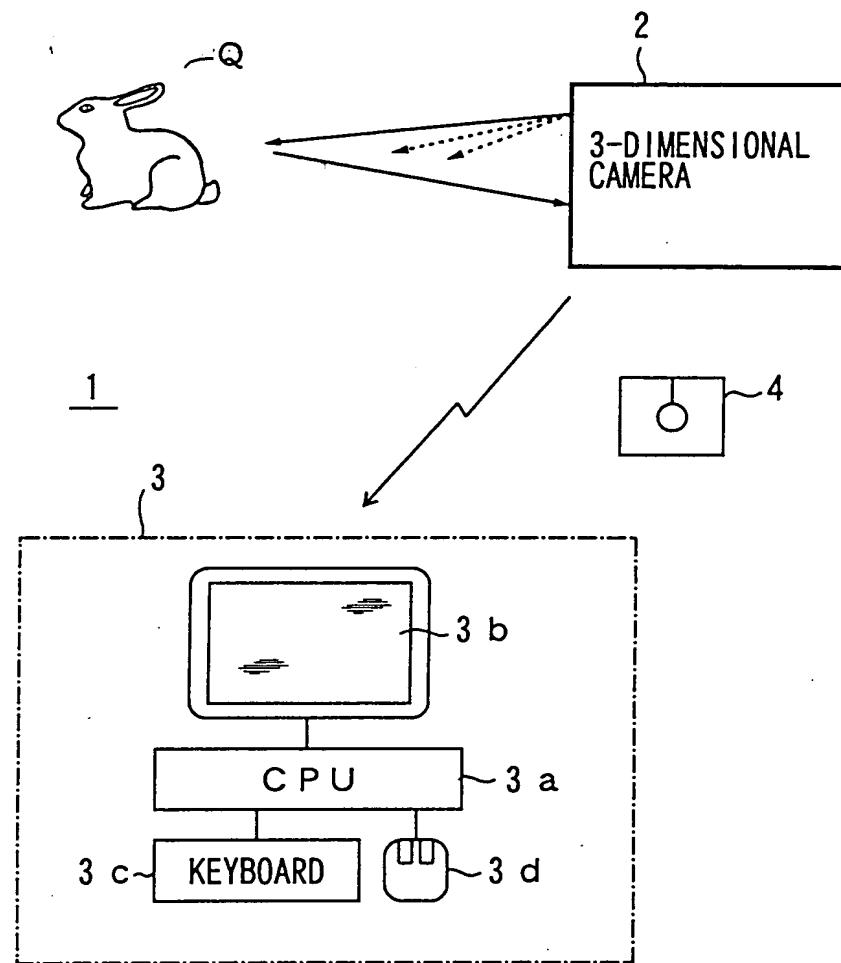


Fig. 1



00000000 00000000 00000000

Fig. 2 A

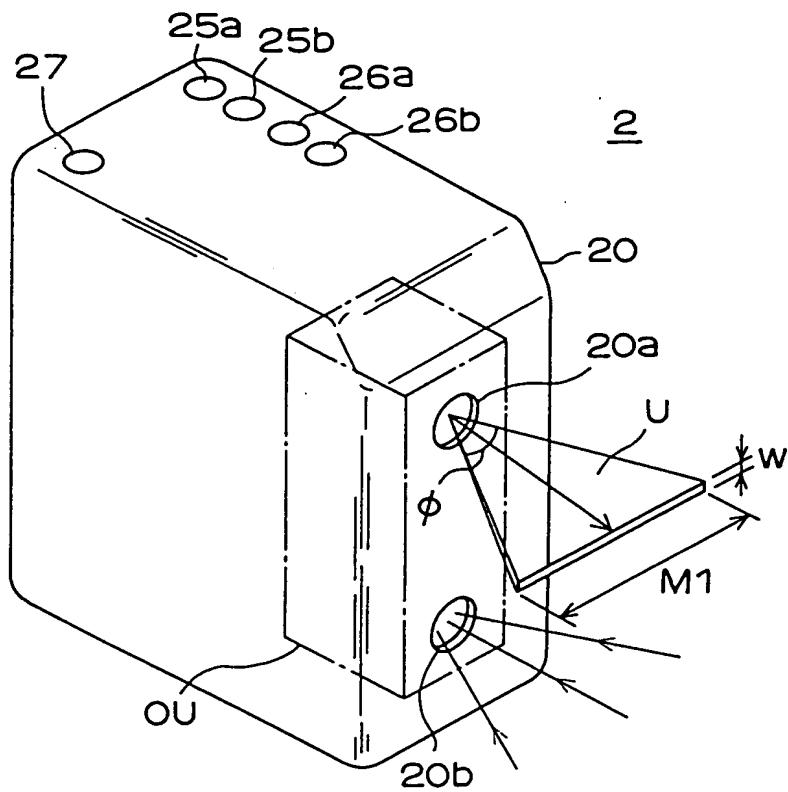
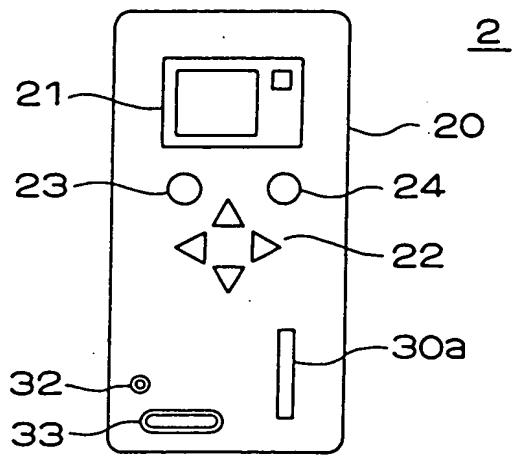


Fig. 2 B



00000000000000000000000000000000

Fig. 3

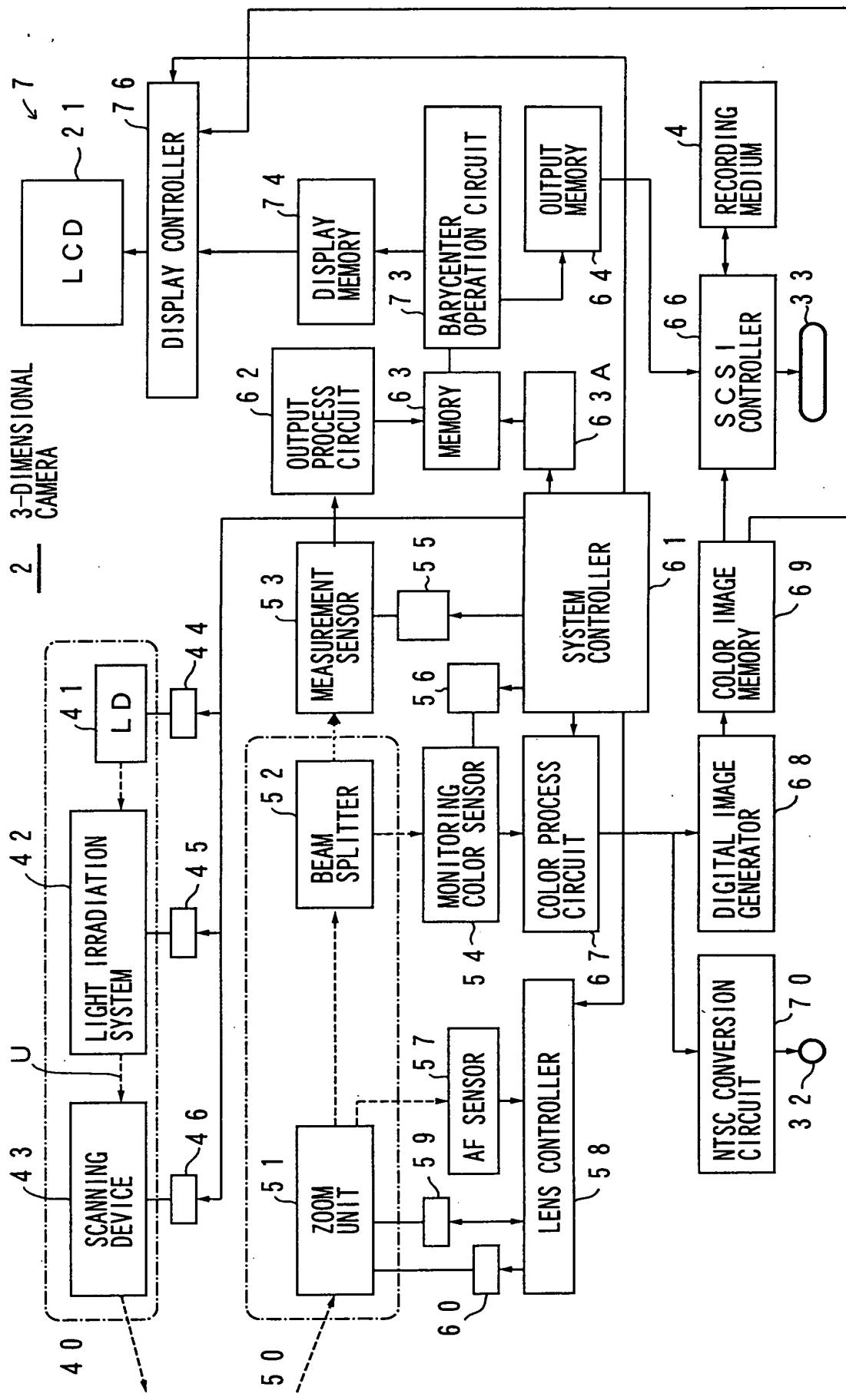


Fig. 4 A

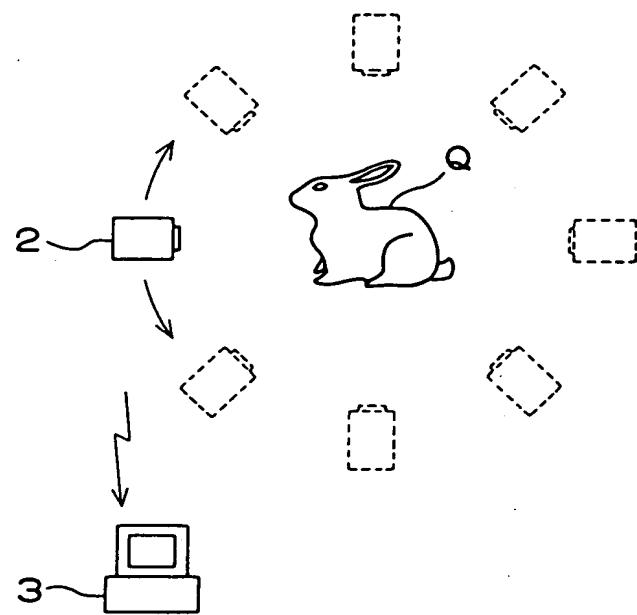


Fig. 4 B

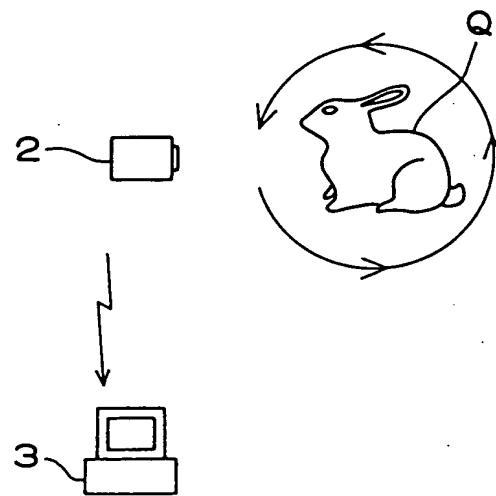
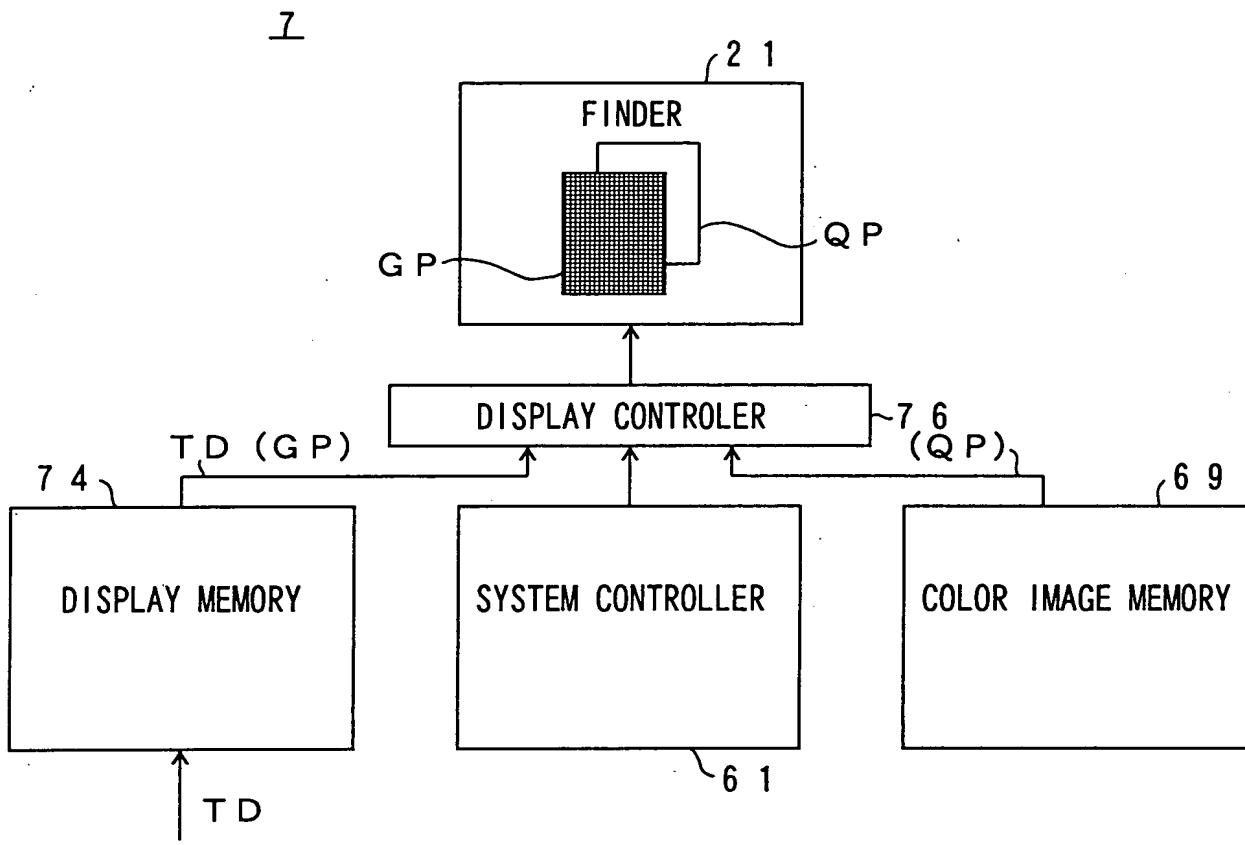


Fig. 5



00000000000000000000000000000000

Fig. 6 A

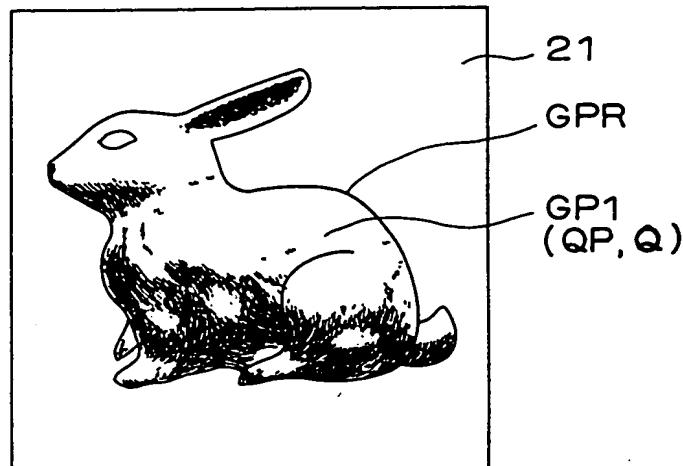


Fig. 6 B

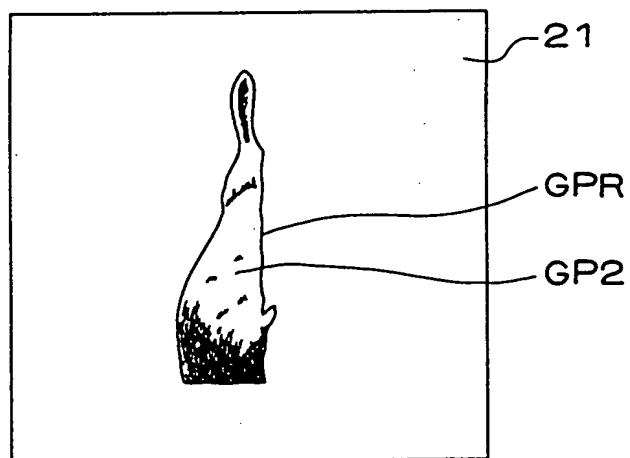


Fig. 6 C

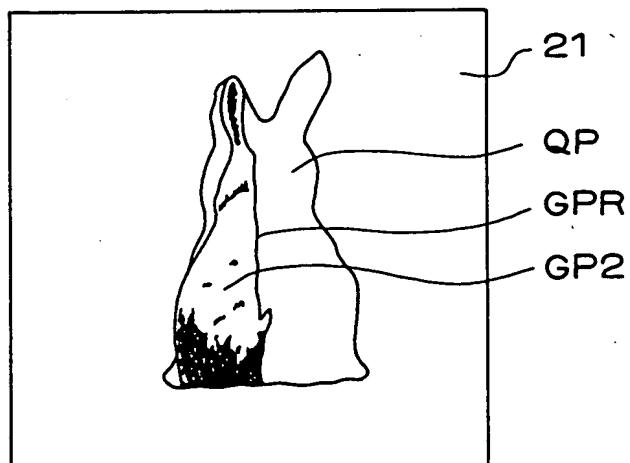


Fig. 7

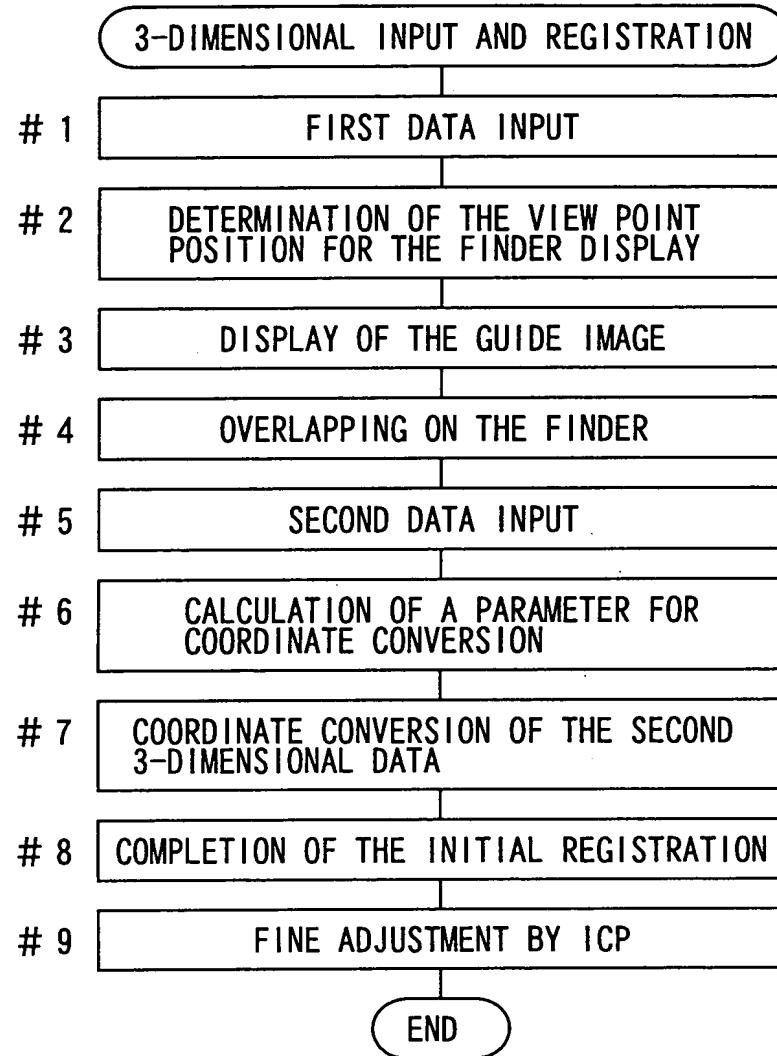
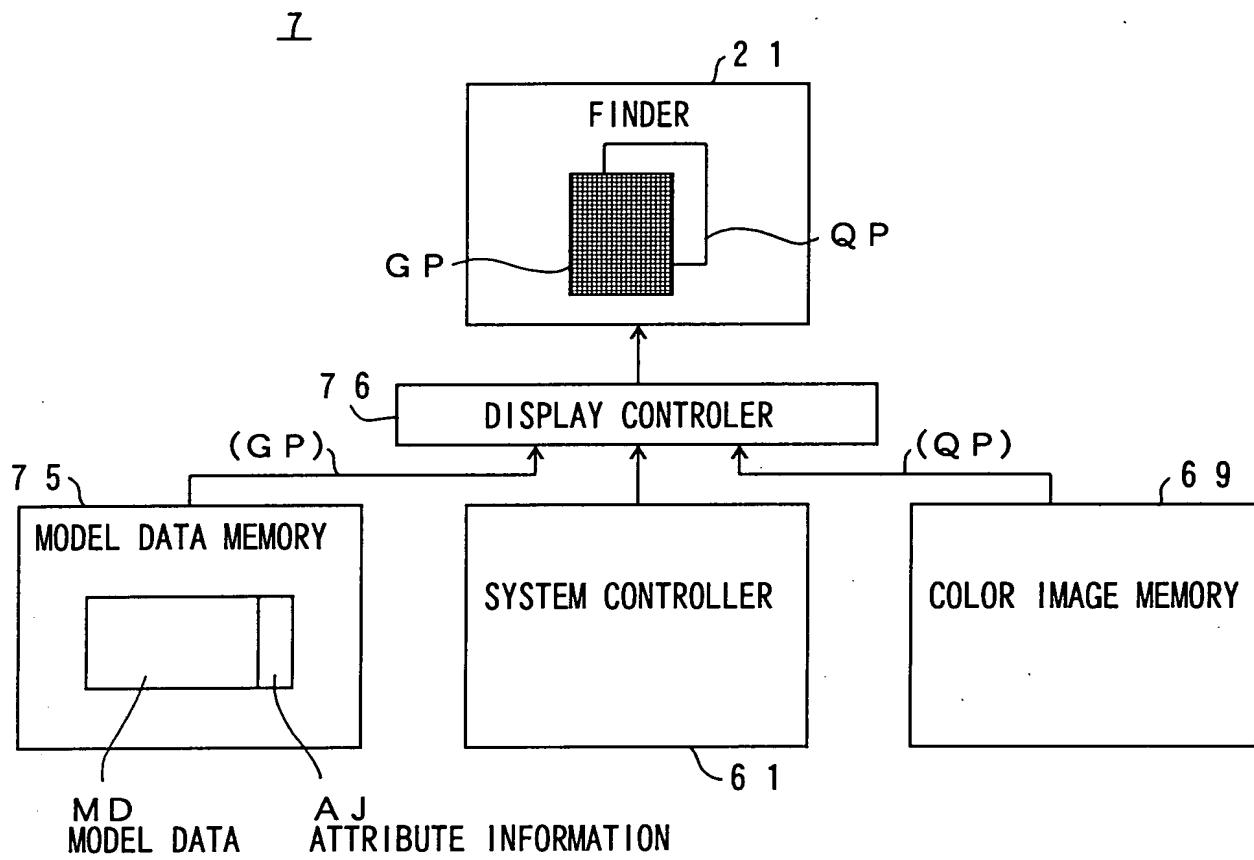
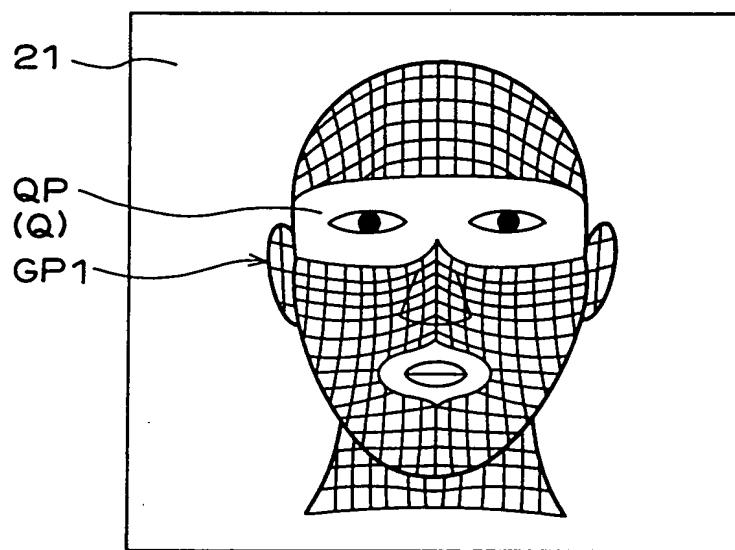


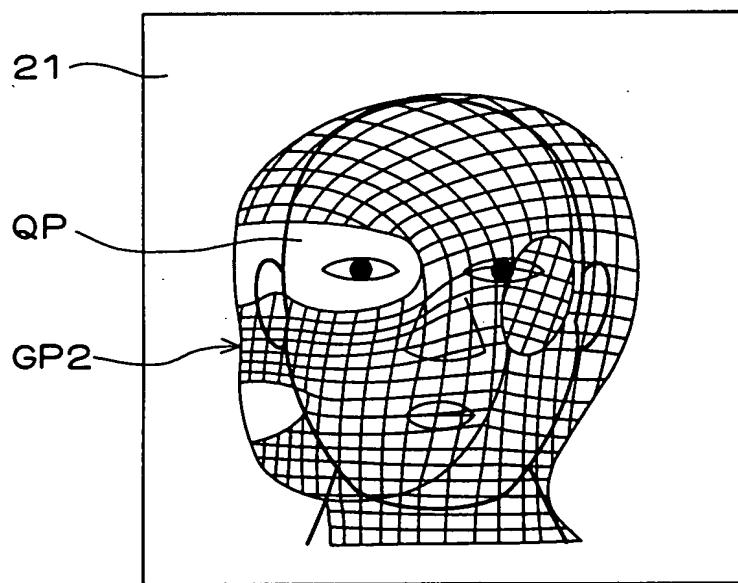
Fig. 8



F i g . 9 A

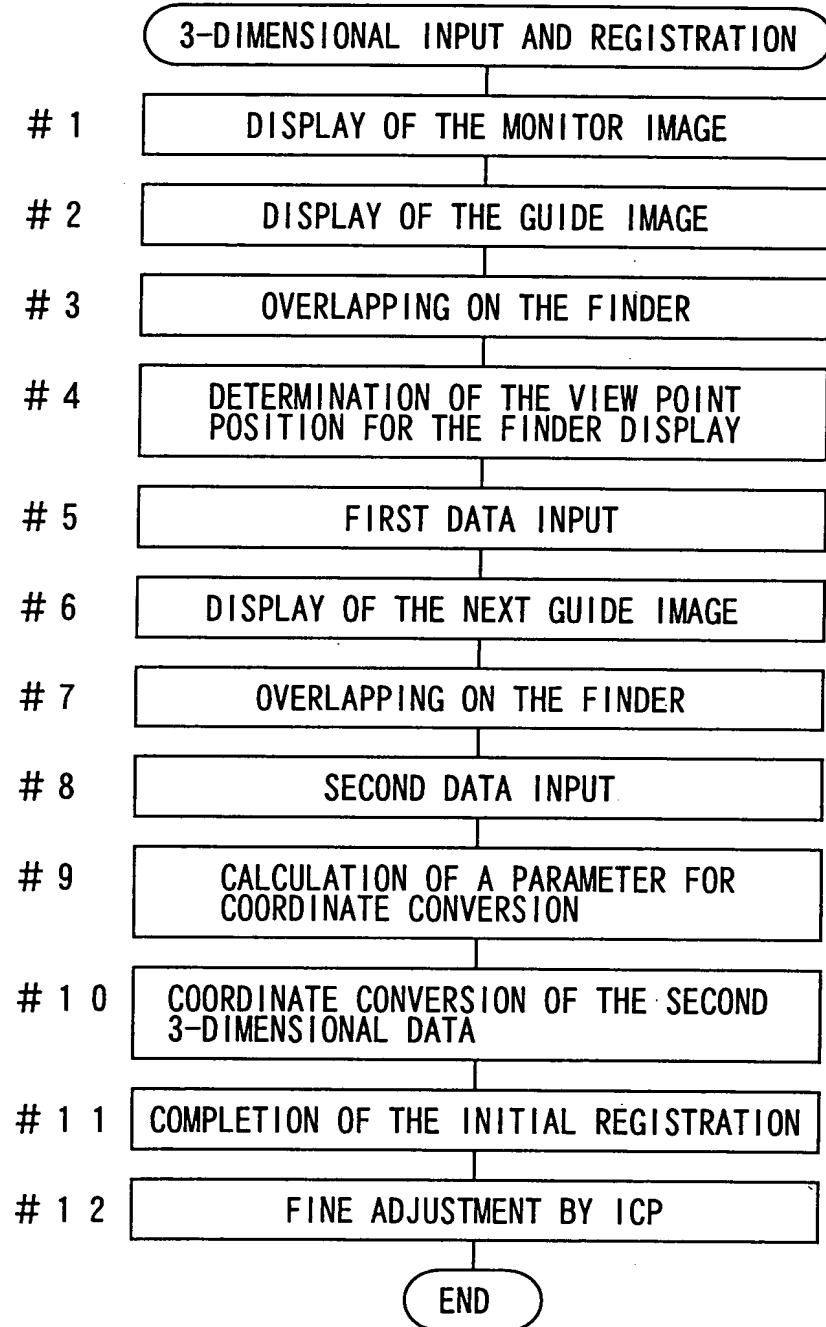


F i g . 9 B



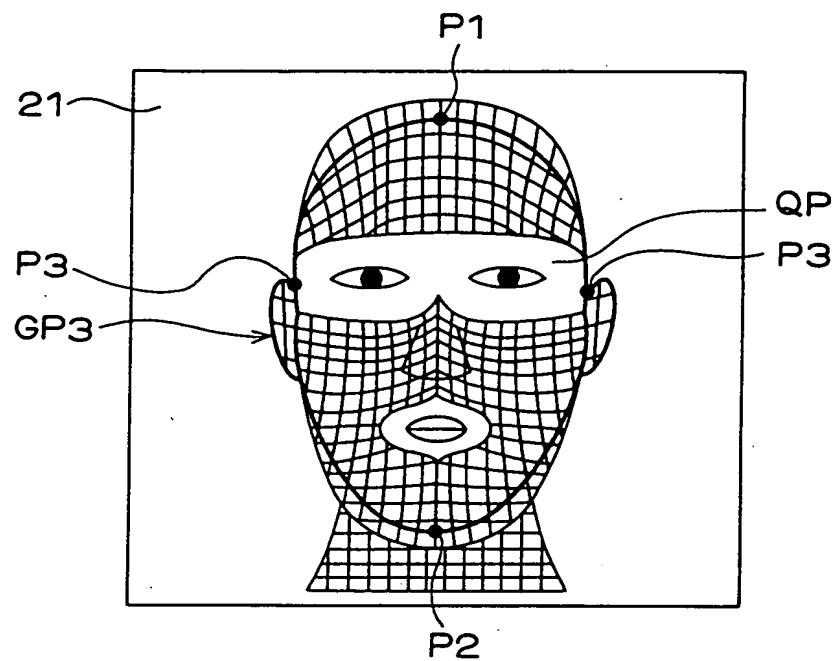
000220-9899600

Fig. 10



ପାତ୍ରାବ୍ଦୀ ପାତ୍ରାବ୍ଦୀ

Fig. 11



## 3-DIMENSIONAL INPUT AND REGISTRATION

- #21 DISPLAY OF THE MONITOR IMAGE
- #22 DISPLAY OF THE GUIDE IMAGE
- #23 OVERLAPPING ON THE FINDER
- #24 MATCHING OF THE ASPECT RATIO OF THE MODEL DATA & OBJECT BY DESIGNATING CORRESPONDING POINTS
- #25 DETERMINATION OF THE VIEW POINT POSITION FOR THE FINDER DISPLAY
- #26 FIRST DATA INPUT
- #27 CALIBRATION OF THE SCALE OF THE MODEL DATA
- #28 DISPLAY OF THE NEXT GUIDE IMAGE
- #29 OVERLAPPING ON THE FINDER
- #30 MATCHING OF THE ASPECT RATIO OF THE MODEL DATA & OBJECT BY DESIGNATING CORRESPONDING POINTS
- #31 SECOND DATA INPUT
- #32 CALCULATION OF A PARAMETER FOR COORDINATE CONVERSION
- #33 COORDINATE CONVERSION OF THE SECOND 3-DIMENSIONAL DATA
- #34 COMPLETION OF THE INITIAL REGISTRATION
- #35 FINE ADJUSTMENT BY ICP

END

F i g . 1 3

